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Legged Robots That Balance | Semantic Scholar

The team engineered the robot as simply a torso and two legs, and designed the system specifically to test lower-body tasks, such as locomotion and balance. As with its full-body counterpart, Little HERMES is designed for teleoperation, with an operator suited up in a vest to control the robot's actions.

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This book, by a leading authority on legged locomotion, presents exciting engineering and science, along with fascinating implications for theories of human motor control. It lays fundamental groundwork in legged locomotion, one of the least developed areas of robotics, addressing the possibility of building useful legged robots that run and balance.

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Line Walking and Balancing for Legged Robots with Point Feet Carlos Gonzalez 1, Victor Barasuol , Marco Frigerio2, Roy Featherstone3, Darwin G. Caldwell3, Claudio Semini1 Abstract—The ability of legged systems to traverse highly-constrained environments depends by and large on the per-formance of their motion and balance controllers. This paper

Line Walking and Balancing for Legged Robots with Point Feet

Two-legged robot mimics human balance while running and jumping. 6. November 2019. Worldwide Spending on Artificial Intelligence Is Expected to Double in Four Years, Reaching \$110 Billion in 2024, According to New IDC Spending Guide - Business Wire ... MC.AI - Aggregated news about artificial intelligence.