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Introduction to Robotics - Sharif

This course provides a mathematical introduction to the mechanics and control of robots that can be modeled as kinematic chains. Topics covered include the concept of a robot's configuration space and degrees of freedom, static grasp analysis, the description of rigid body motions, kinematics of open and closed chains, and the basics of robot control.

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Introduction to Robotics: Analysis, Control, Applications ...

Over all, I would say this is the best source for understanding mechanics and control theory as it relates to robotics motion. It really gets into the details that books on the subject of computational robots such as "Introduction to Autonomous Mobile Robots" and "Computational Principles of Mobile Robotics" simply do not have the room to accommodate.

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Robot control systems are usually much more complex than programmable automata, which were used earlier to control simple pick-and-place manipulators.